

# AERODYNAMICS OF VEHICLES IN VACUUM TUBE SYSTEMS

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*HEPIA Geneva Wind Tunnels*

Vacuum Transport Seminar  
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# 1. INTRODUCTION – VACUUM TUBES, WHY?

**Challenges** : « High speed with less resistance ». However, in Switzerland other aspects are also interesting:

- Less surface on the ground. Less objections for project applications!
- Less noise pollution
- Environmentally friendly(?) → Depend on project choices!

**History** : Not a new idea! Some projects are:

- 1960 **Office for High Speed Ground Transportation (USA)**, projects at the Jet Propulsion Lab (CalTech), MIT, Illinois Institute of Technology, ecc.
- 1974 **Institut Battelle** « The quiet Tube Train »
- 1975 **Illinois Institute of Technology**, « Pneumatic air vacuum propulsion system »,
- 1994 **EPFL**, Swissmetro SA, Prof. Marcel Jufer
- 2013 **Hyperloop**, SpaceX, Hyperloop Alpha Description, then student competition, several projects in the world.
- 2015 Actually projects exist in numerous countries, also in Switzerland. Delft, Canada, EPFL, Eurotube Foundation, ecc.

L'avenir est à créer

# 1. INTRODUCTION

## HES-SO PROJECT OBJECTIVES

Complete the work done by the actual actors, on subjects not completely covered, and in the competences of university of applied sciences:

- Integration in the Swiss transport policy
- Socio-cultural acceptance
- Industrial dimensioning (maintenance, costs, investments)
- Safety (in regard of the operation of a vacuum train?)
- Developement of methodology for aerodynamics, thermal aspects, electricity management, sustentation, propulsion, composite structure.
- Support for Eurotube Foundation projects

Offer these knowledge in a vaccum tube transport project.

 **HES-SO Project GRIPIT**

# 1. INTRODUCTION - HES-SO PROJECT GRIPIT

## Groupe de Recherche Interdisciplinaire en Projets Innovants de Transport (GRIPIT)

- **Prof. Samuel Chevailler**, HES-SO//Valais (magnetic levitation, motors)  
Electromagnetism and electrical energy, project manager
- **Prof. Joël Cugnoni**, HEIG-VD (ex. Hyperloop EPFL)  
Multifunctional structure, composite materials
- **Prof. Carole Baudin**, HE-ARC  
Anthropotechnology, socio-cultural context
- **Prof. Vincent Bourquin**, HEIA-FR (ex. Swissmetro SA 1990, Prof. Jufer)  
Systemic model, safety
- **Prof. Patrick Haas**, HEPIA (ex. ARD SA, Bombardier Inc., Eurotunnel)  
Aerodynamic, thermal, safety

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## 2. AERODYNAMICS

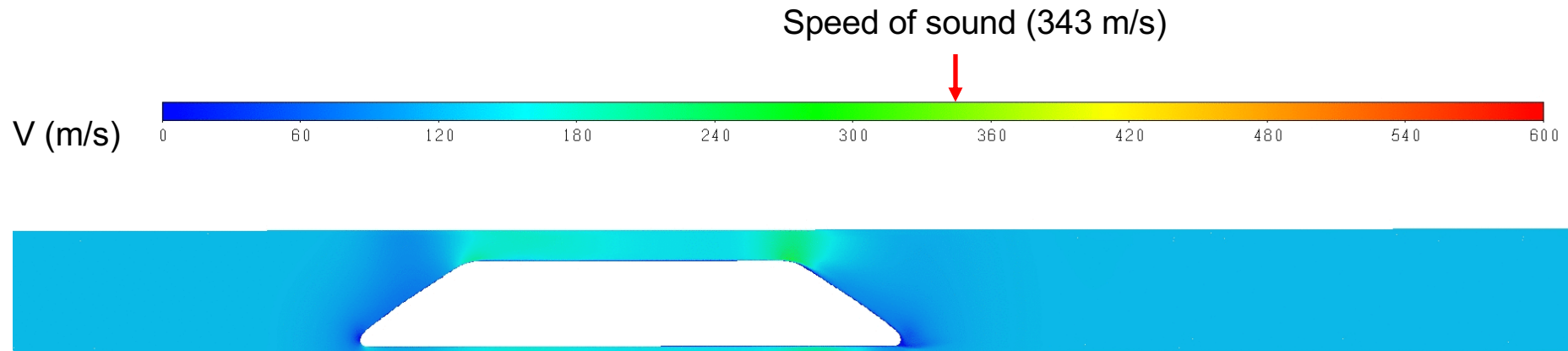
Demystifying beliefs! Physics tells us:

- The vacuum is not enough to go fast!
- The drag is proportional to the density in subsonic regime.
- In supersonic (high blocking ratio, i.e. small tunnel) :
  - ➔ Sonic blocking appears!
- The speed of sound is then the sensitive parameter. It is not possible to go much beyond this one.
- Thermal ? How to cool a machine dissipating 50 to 500 kW in vacuum?  
At 100 Pa (1 mbar),  $\Delta T$  are multiplied by 1'000 !

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## 2. AERODYNAMICS

### MOTION OF VEHICLES IN TUNNELS



Concept\_00 3d, V amont = 150 m/s, T0 = 20 ° C, P0 1'000 Pa



Contours of Velocity Magnitude [m/s] (Time=1.0000e-02 s)

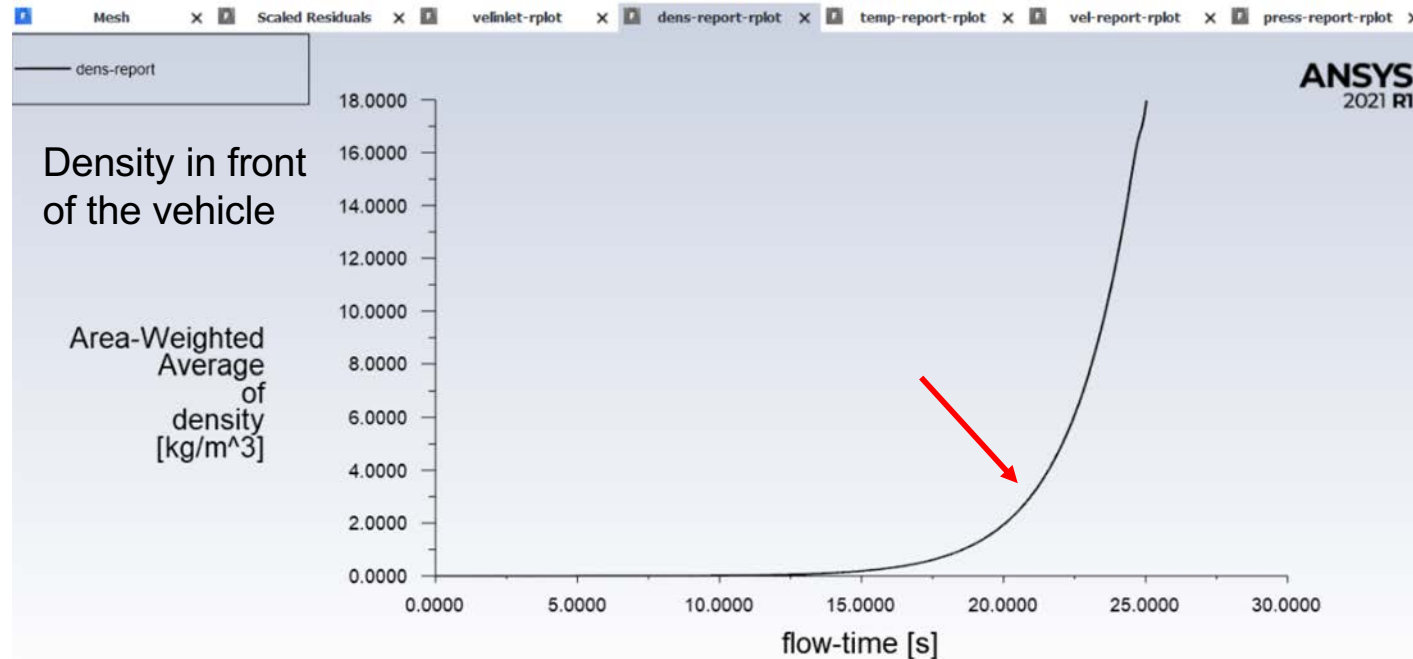
ANSYS Fluent 2021 R1 (3d, dbns imp, sstk, transient) Jun 03, 2021

- The speed of sound is reached in the annular section
- Presence of shock waves and expansions downstream of the vehicle (supersonic regime)
- Constancy of the Mach number in the annular section (Ma 1.0)
- The speed does not evolve significantly whatever the upstream pressure !

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## 2. AERODYNAMICS

### EVOLUTION OF VARIABLES AND SONIC BLOCKING

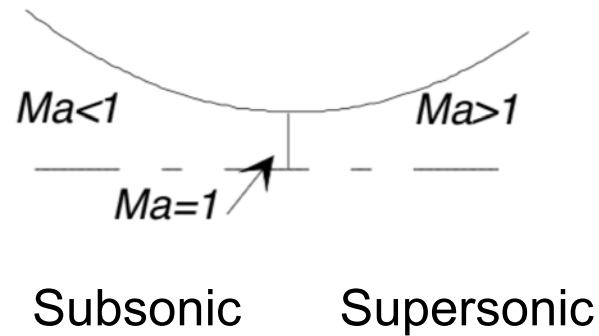
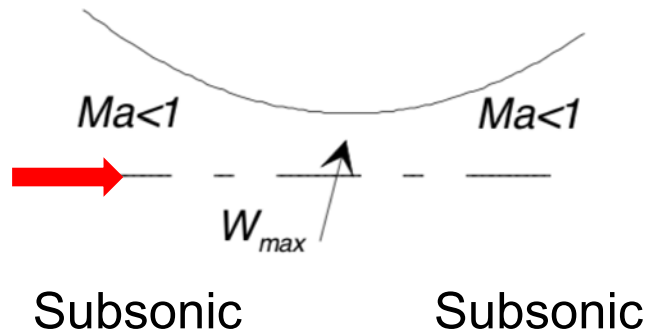


→ **Sonic blocking**

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## 2. AERODYNAMICS

### FLOW IN A CONVERGENT - DIVERGENT SECTION

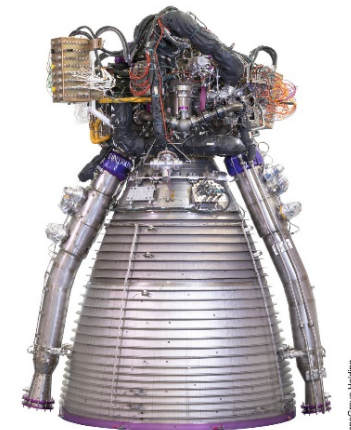


Soyouz rocket

Hugoniot theorem

$$\boxed{(Ma^2 - 1) \cdot \frac{dW}{W} = \frac{dS}{S}}$$

➔ Relation between Ma and section S



Vulcain motor - Ariane

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## 2. AERODYNAMICS – SONIC BLOCKING

Hugoniot theorem

$$(Ma^2 - 1) \cdot \frac{dW}{W} = \frac{dS}{S}$$

$$Ma = \frac{W}{a} \quad a = \sqrt{\kappa r T}$$

- When the speed  $W$  reaches the speed of sound  $a$  in the annular section, the vehicle is "blocked"! The supersonic regime starts.
- At the nozzle throat  $dS = 0$  and therefore  $Ma = 1.0$ .  $W = a$  (speed of sound) always!
- • The speed of sound is not influenced by the pressure! It is a function of the **gas characteristics  $\kappa$ ,  $r$  and temperature**.
- So the **pressure is not the determining criterion** if you want to go fast!
- It only reduces the drag in subsonic regime. The problem is that the sonic limit is obtained soon for a high blockage ratio ( $> 0.40$ ).

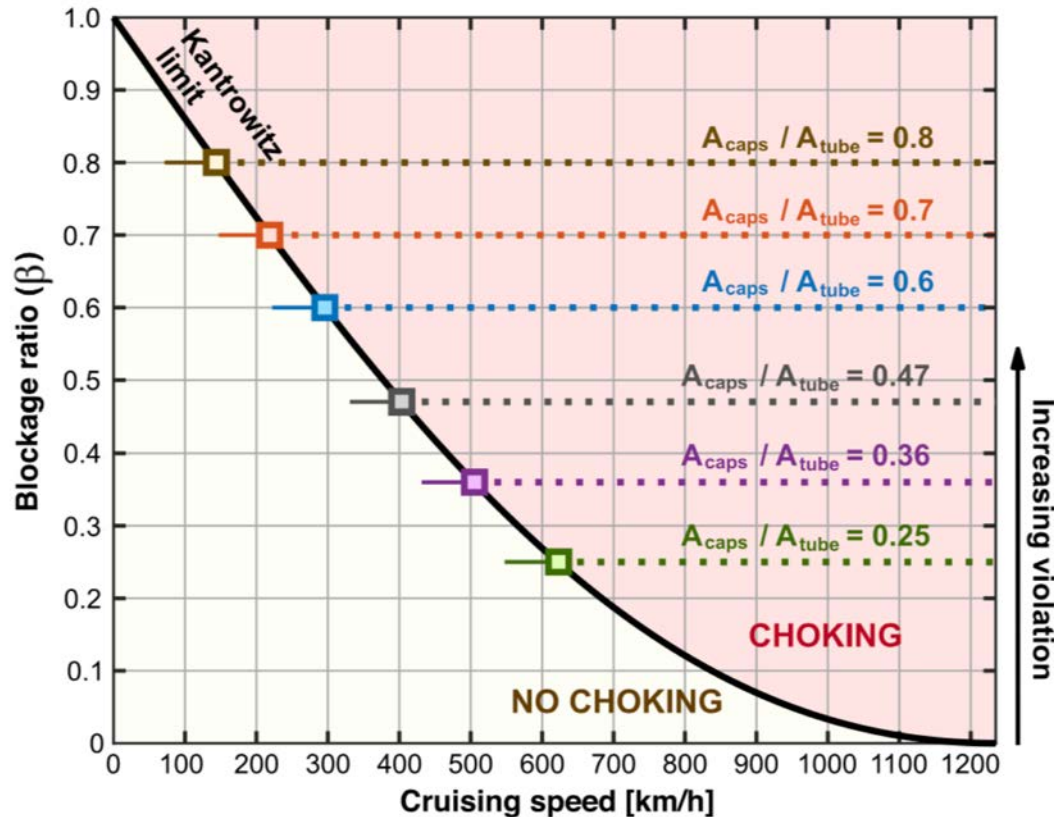
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## 2. AERODYNAMICS – SONIC BLOCKING

When we use a blocking ratio, we introduce the Kantrowitz limit:



$$\frac{1}{1 - \beta} = \frac{1}{\text{Ma}} \left( \frac{1 + \left[ \frac{\gamma - 1}{2} \right] \text{Ma}^2}{1 + \left[ \frac{\gamma - 1}{2} \right]} \right)^{\frac{\gamma + 1}{2(\gamma - 1)}}$$


Blockage ratio:

$$\beta = \frac{\text{Vehicle section area}}{\text{Tunnel section area}}$$

(J.K. Noland, NTNU, Values at 15 degC)

### 3. DISCUSSION ON THE TUNNEL ENVIRONNEMENT

Our argument is as follows:

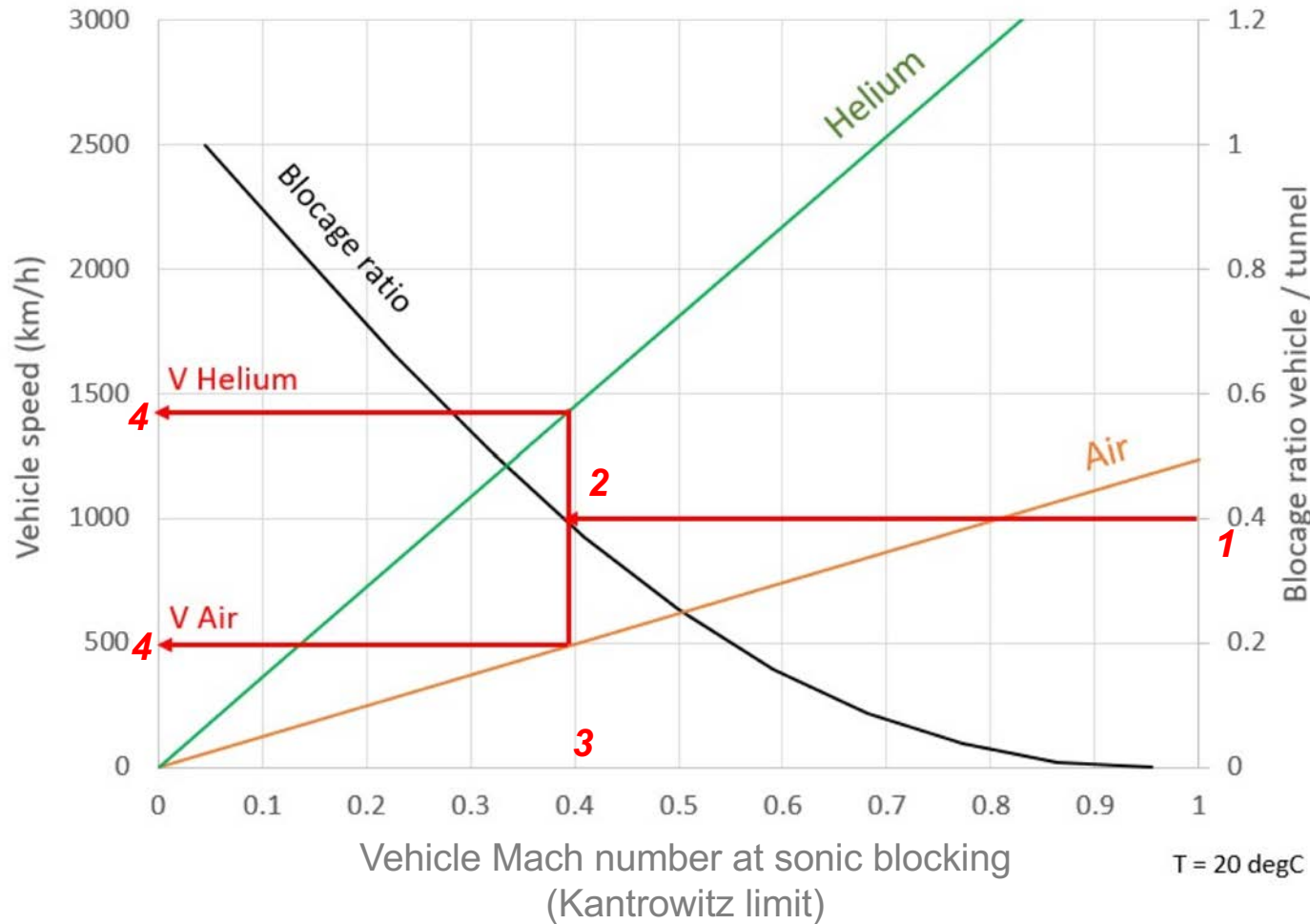
1. We should come back to the hypothesis regarding the environment. If a closed environment is realized, it is necessary to go further than making the vacuum. We should act on the sensitive parameters who are the characteristics of the gas ( $C_p$  and  $C_v$ ) and the temperature !
2. Our objective is to increase the speed of sound ( $> 800$  m/s)  
 Allow the use of smaller tunnels (high blockage ratio)
3. Our research is directed beyond the use of air under vacuum at room temperature:
  - We look for other gases: Helium, Hydrogen, mixtures
  - Higher temperatures
  - Two-phase fluid (cooling by evaporation/condensation, water evaporates at about  $7^\circ\text{C}$  at  $1'000$  Pa).

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### 3. DISCUSSION ON THE TUNNEL ENVIRONNEMENT



Example:

Si  $A_v / A_t = 0.40$   
Kantrowitz: Ma 0.40



Air : 500 km/h  
Helium : 1'400 km/h

**➔ EXPLORE THE USE OF HELIUM !**

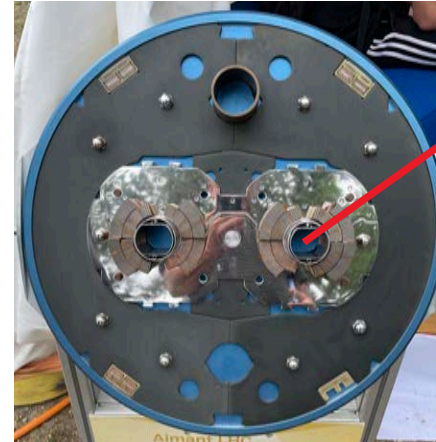
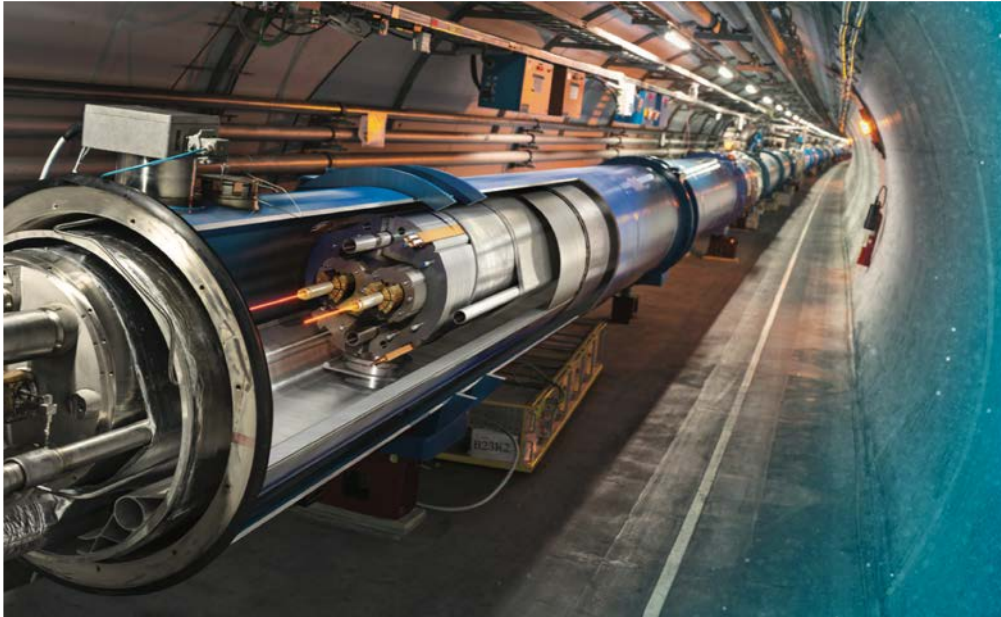
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### 3. DISCUSSION ON THE TUNNEL ENVIRONNEMENT

Is it reasonable to use helium? Large industrial projects exist. CERN surely has things to show.



$P = 10^{-13}$  bars  
 $T = 1.9$  K  
 $L = 27$  km

CERN LHC

- A better vacuum than on the moon! They know how to extract fluid particles from a tube!
- Imagined in 1980, work started in 1994! Operational in 2010 !
- More difficult things: Helium disponibility for industry?

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## 4. METHODOLOGY USED AT HEPIA-CMEFE

Our group develops multidisciplinary methodologies of **CFD simulations** and **experimental works** in parallel.

### Chapter 1: CFD

#### Calculation tools:

##### With UNIGE :

**Baobab HPC** : 4'200 CPU, 95 GPU, 10 Tb RAM

Intel Sandy Bridge, Broadwell and Cascade Lake,

**Yggdrasil HPC** : 4'300 CPU, 52 GPU, 10 Tb RAM,

Intel Gold

##### Group Workstations:

**EoleC6**: Dell, 96 CPU, 512 Gb RAM

**Workstations**: 1 x WS of 48 CPU, 384 Gb et 8 x WS of 16 CPU, 126 Gb RAM

**Storage (NAS)**: 2 x 120 Tb = 240 Tb, management of confidentiality

**CFD software**: ANSYS CFD Associate (« industrial »), Research and Teaching –

ANSYS Academic Partner



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## 4. METHODOLOGY USED AT HEPIA-CMEFE

### Chapter 2: Experimental – AEROTUBE

A supersonic wind tunnel for the aerodynamics of vehicles in tunnels:



GRIPIT Concept\_00  
diam. 47 mm

- Air tank: 20 m<sup>3</sup>, 16 bars, 100 degC, blasts of 60 sec
- Test section 8 x 12 cm<sup>2</sup>
- 0.8 < Ma < 2.4
- Measurement of Ma, pressures and temperatures
- Test done in Ma similitude, scale approx. 1:50

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## 5. CFD ANALYSIS

Validity of a finite volumes CFD approach in vacuum

Knudsen number:  $Kn = \frac{\lambda}{L}$        $\lambda = \frac{\mu}{P} \sqrt{\frac{\pi RT}{2M}}$

L	Length characteristic
$\lambda$	Free movement length of a particle
$\mu$	Dynamic viscosity Pa.s
P	Pressure Pa
R	Gaz constant 8,314 J.K <sup>-1</sup> .mol <sup>-1</sup>
M	Molecul mass kg.mol <sup>-1</sup>

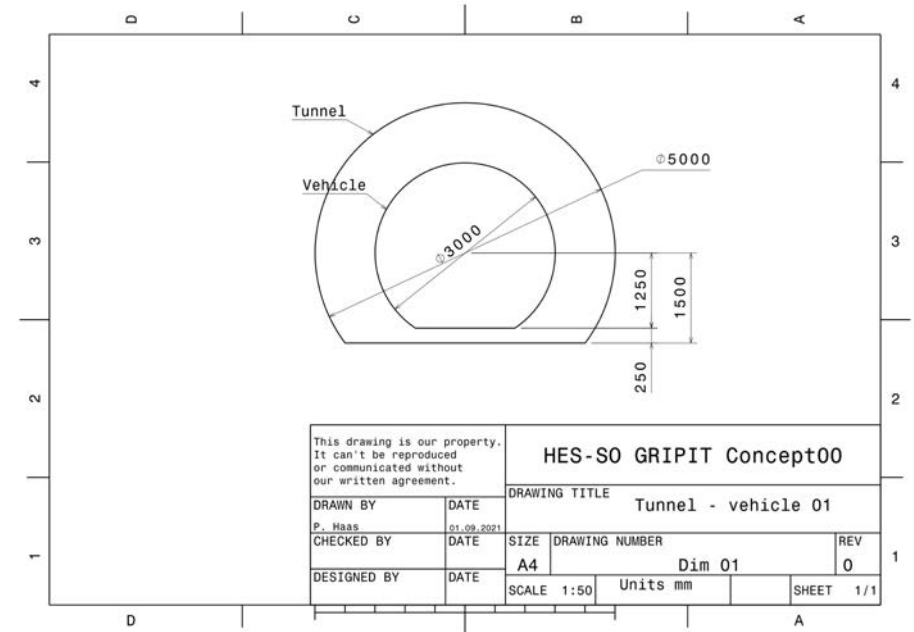
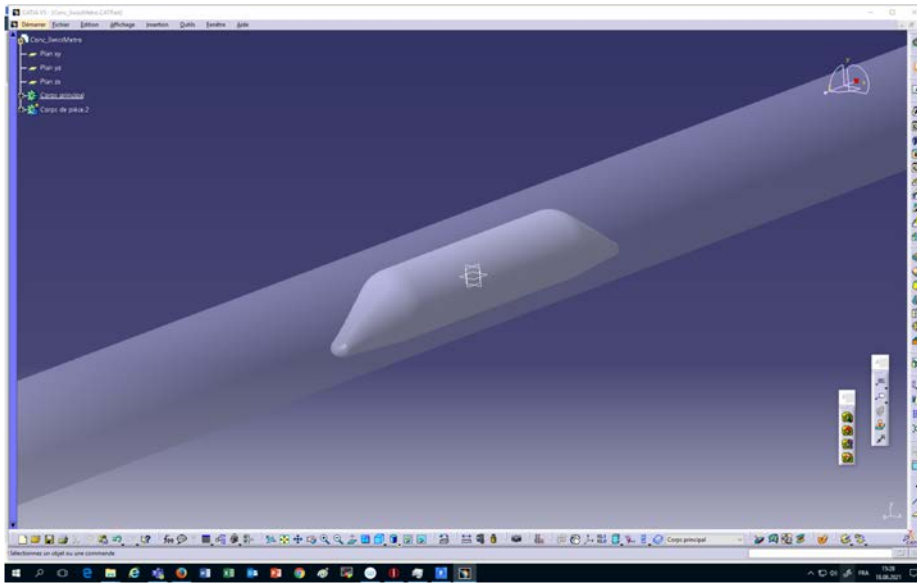
- The medium is said to be **continuous**, and a finite volume solver usable, if  **$Kn < 0.01$** . This is the case!
- Remark: In Fluent, the "Low-pressure boundary slip" model in "Turbulence / Laminar", allows to work between  $0.01 < Kn < 0.1$ .

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## 5. CFD ANALYSIS

### Vehicle geometry, base case



Concept\_00 (simple, inspired Swissmetro 1990)

Section vehicle :  $6.8 \text{ m}^2$

Section tunnel :  $16.8 \text{ m}^2$

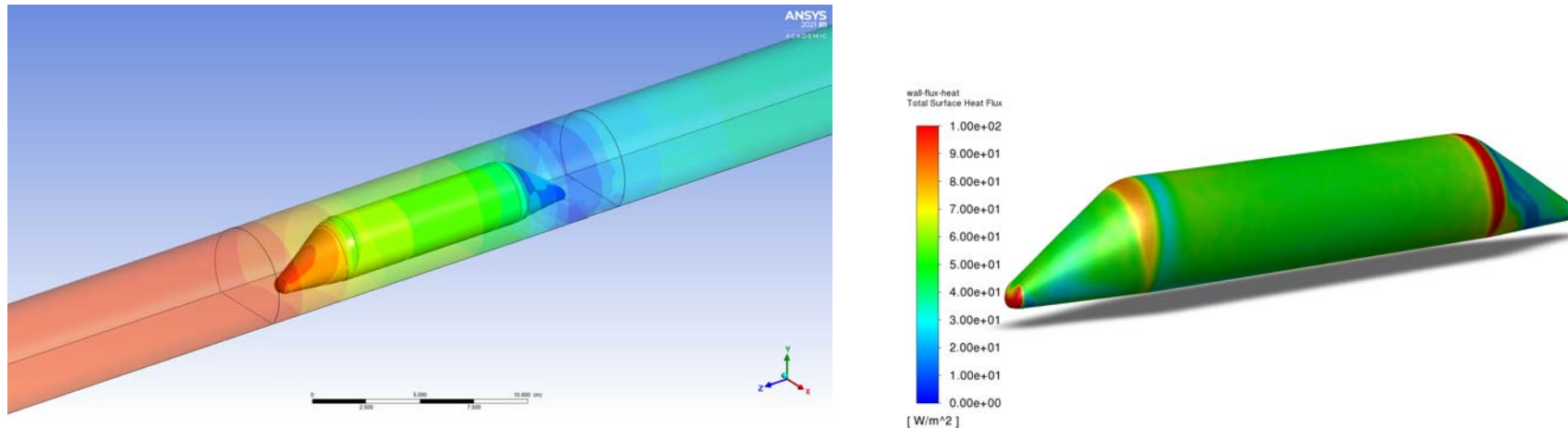
Blockage ratio : 0.40

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## 5. CFD RESULTS

Preliminary results with Concept\_00 to understand the evolution of some quantities (Fluent solver, k-w SST model, compressible, unsteady).  
Computing time: About 1/2 day, 48 cores.

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- Forces and moments
- Convection
- Pressures (distribution)
- Unsteady phenomena



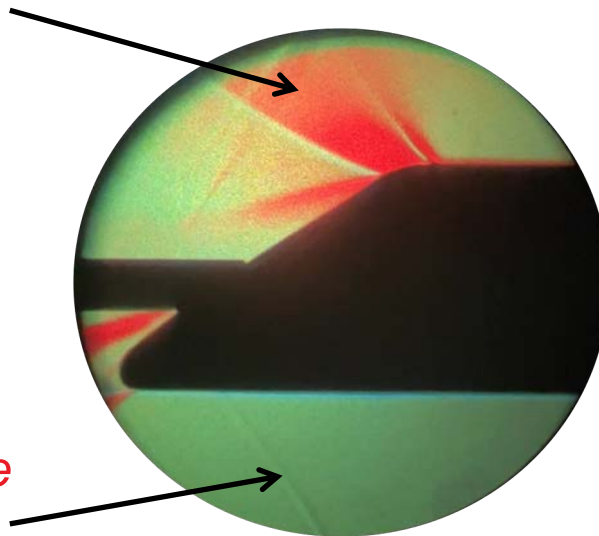
Vehicle dynamic study  
Thermal study  
Structure design  
Tunnels, fatigue, installations

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## 5. CFD - RESULTS

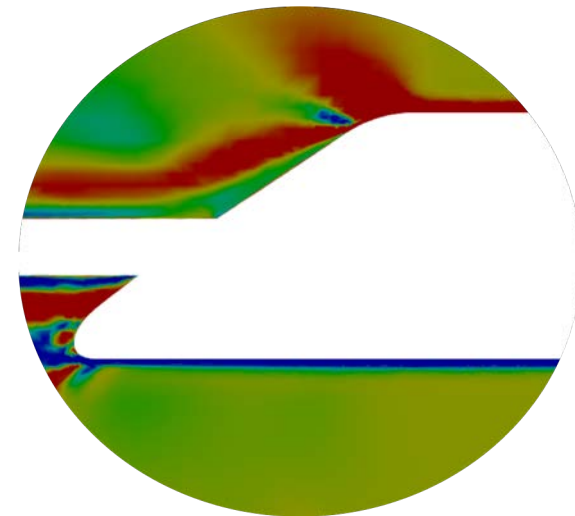
### CFD Validation using Aerotube results

*Prandtl-Meyer  
discharges*



*Small Mach wave  
generated by a  
tunnel rugosity*

**Aerotube experiment**  
Schlieren optical system



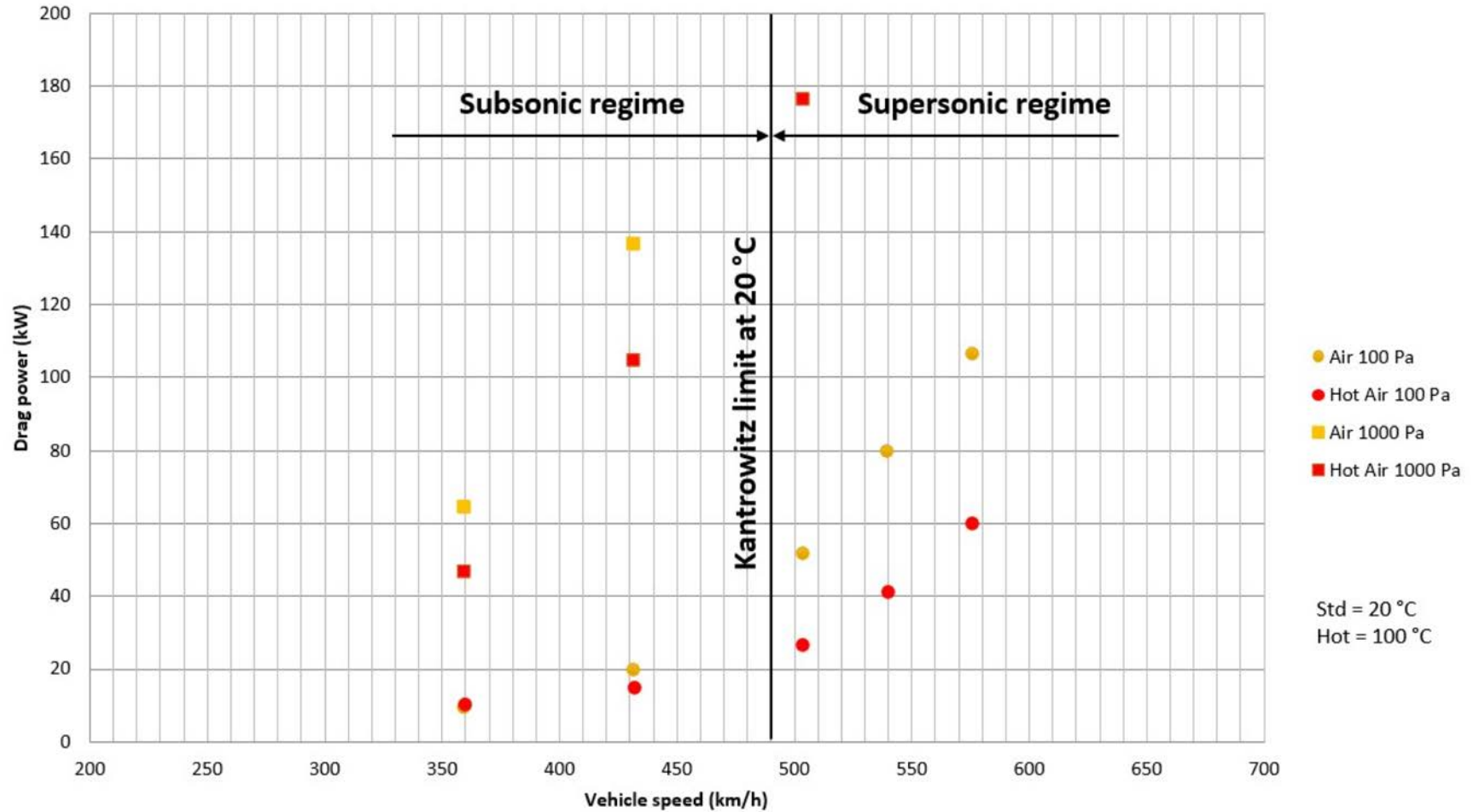
**CFD simulation**  
Air density gradient

Concept\_00  
Blockage ratio: 0.40

# 5. CFD - RESULTS

## Aerodynamic drag

Air



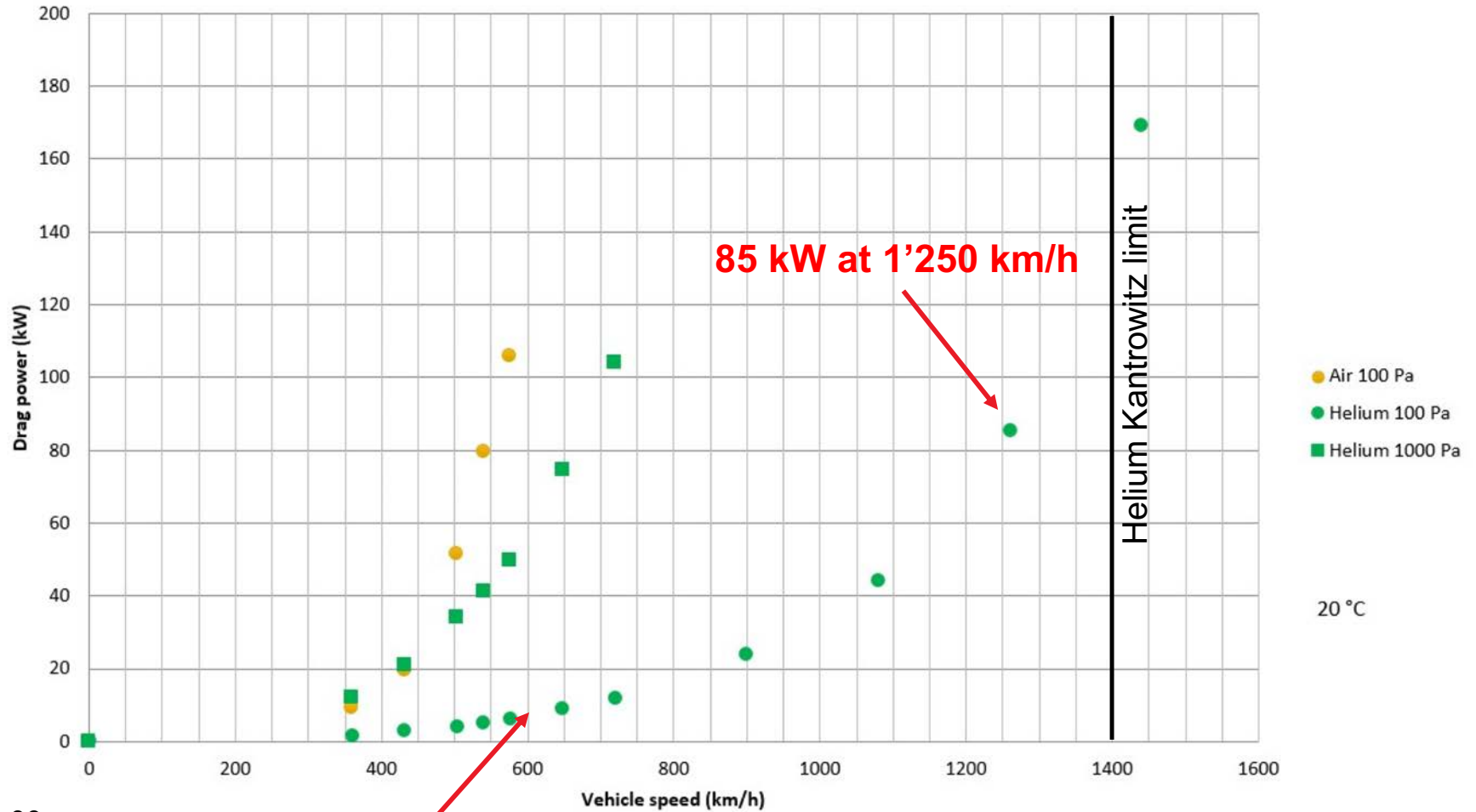
Concept\_00  
Blockage ratio: 0.40

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# 5. CFD - RESULTS

## Aerodynamic drag

Helium



Concept\_00  
Blockage ratio: 0.40

7 kW at 600 km/h

85 kW at 1'250 km/h

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## 6. WHAT SOLUTION TO CHOOSE?

We can imagine the following projects:

### 1. « Classical » air project:

$V = 600 \text{ km/h}$

Blockage ratio: 0.40 (tunnel diameter 5.0 m)

Aerodynamic power: 130 kW

### 2. High speed helium project and small tunnel (low investment):

$V = 1'000 \text{ km/h}$

Blockage ratio: 0.60 (tunnel diameter 4.4 m)

Aerodynamic power: 100 kW

### 3. Low energy helium project:

$V = 600 \text{ km/h}$

Blockage ratio: 0.40 (tunnel diameter 5.0 m)

Aerodynamic power: 7 kW

Magnetic drag of sustentation ? Wheels?

*(These values are for 100 Pa and 20 ° C)*

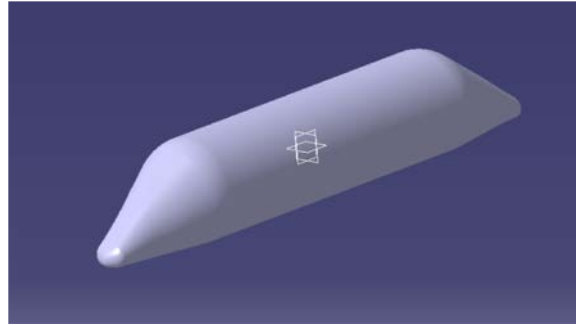
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## 7. CFD RESULTS – GEOMETRY OPTIMISATION

Concept\_00  
Swissmetro 1990



Step 1



Concept\_01  
Haack's ogive



Haack's ogive

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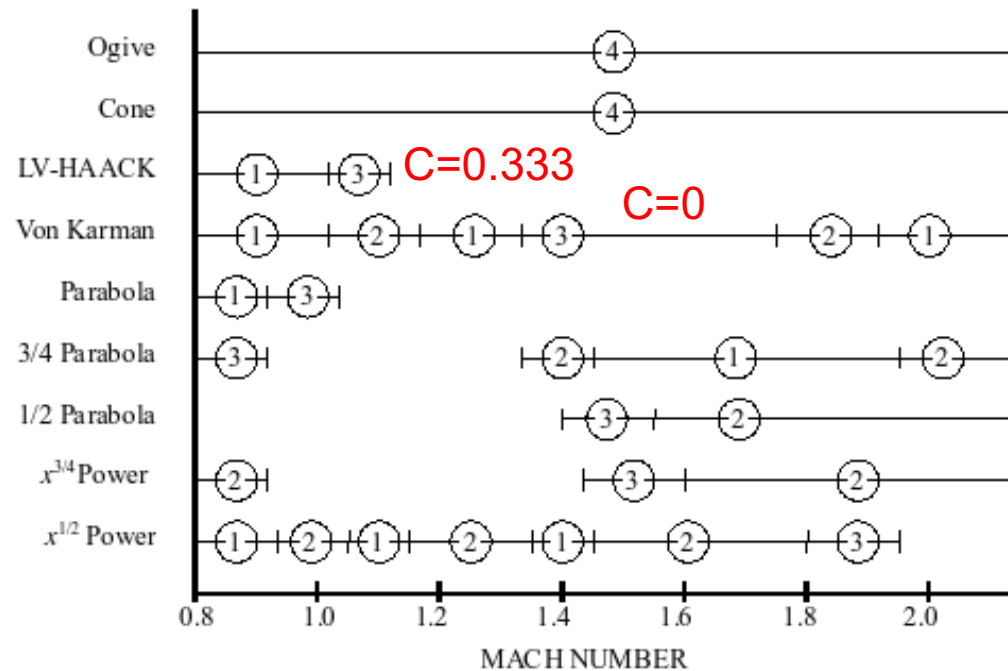
# 7. CFD RESULTS – GEOMETRY OPTIMISATION

Haack's theory:

We choose the von Karman one with  $C = 0$  for best performances in transonic regime

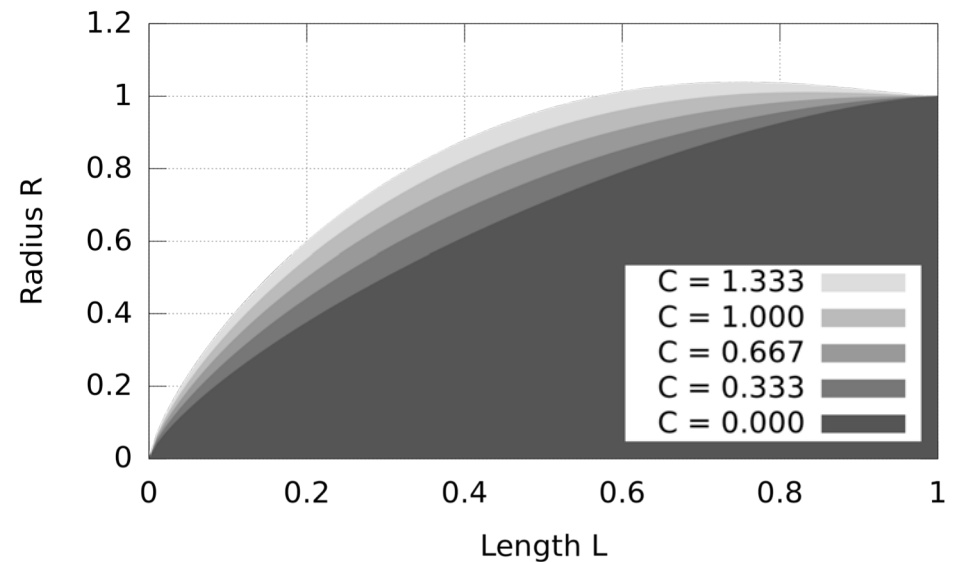
$$\theta = \arccos\left(1 - \frac{2x}{L}\right)$$

$$y = \frac{R}{\sqrt{\pi}} \sqrt{\theta - \frac{\sin(2\theta)}{2} + C \sin^3(\theta)}$$



(Performance parameter: 1 good to 4 bad)

Nose Cone Haack Series



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## 7. CFD RESULTS – GEOMETRY OPTIMISATION

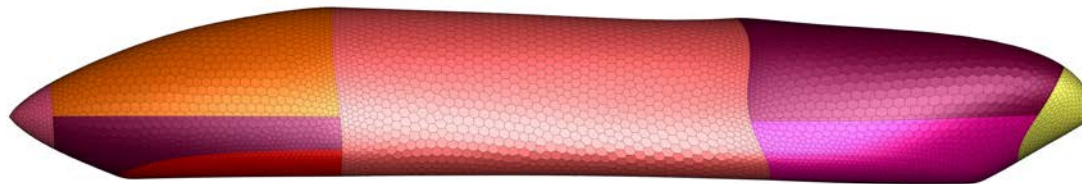
Concept\_01  
Haack's ogive  
( $C = 0$  von Karman,  
two ends)



Step 2

CFD automatic optimisation  
using a gradient based model

Concept\_02  
HES-SO ogive



Optimized geometry

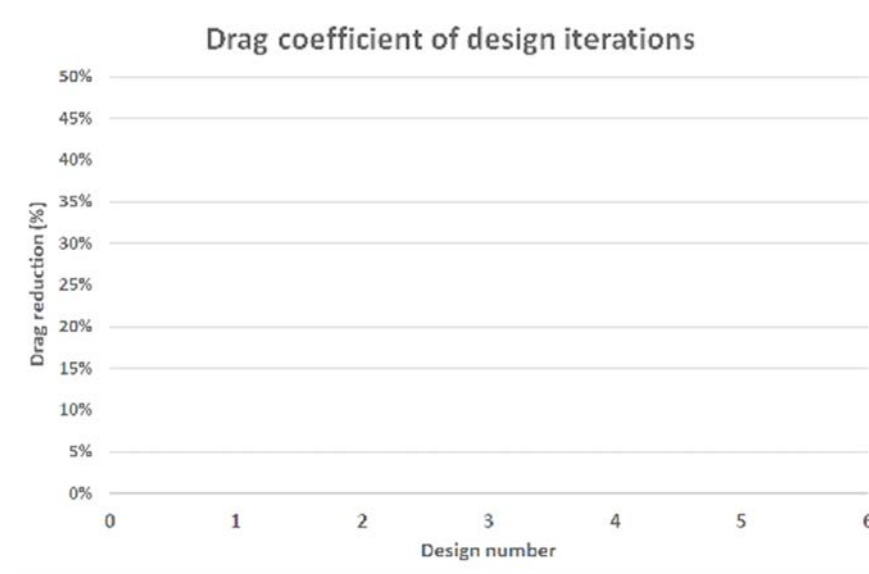
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## 7. CFD RESULTS – GEOMETRY OPTIMISATION

- The changes reflect 3D effects: The Haack's ogive is 2D axisymmetrical
- Our vehicle has two ends: The Haack's ogive second end is flat (projectile)



V = 600km/h  
P = 100 Pa  
Blockage = 0.25  
Mach col = 0.95

- Gradient based optimizer
- Second order: pressure and movement
- Ideal gas



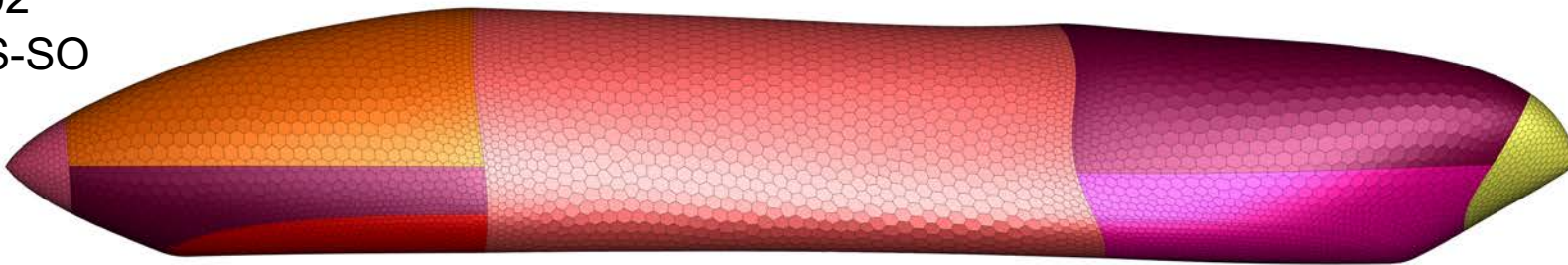
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## 7. CFD RESULTS – GEOMETRY OPTIMISATION

Concept\_01  
Haack's ogive



Concept\_02  
Ogive HES-SO



Front end with  
small changes

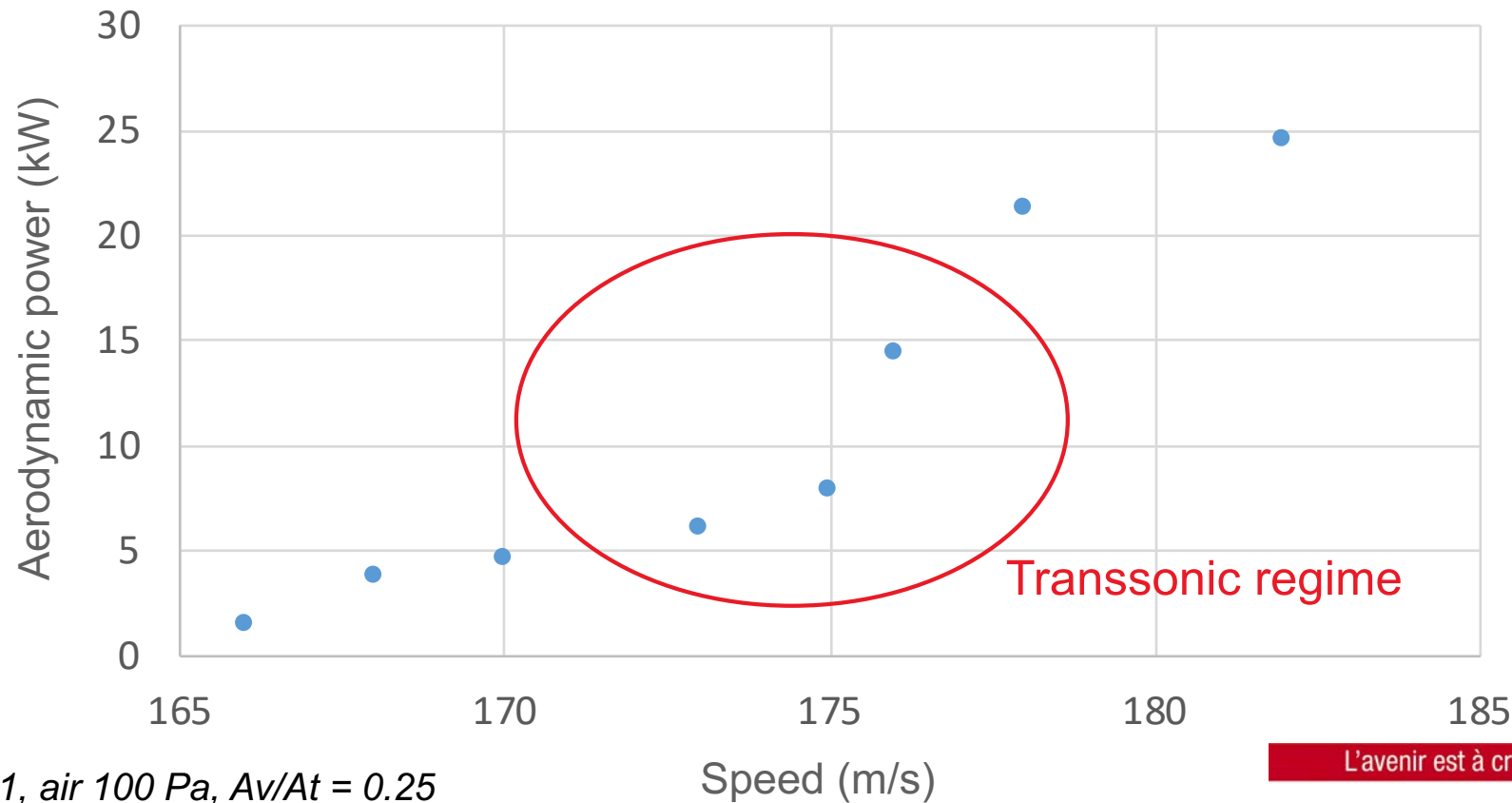
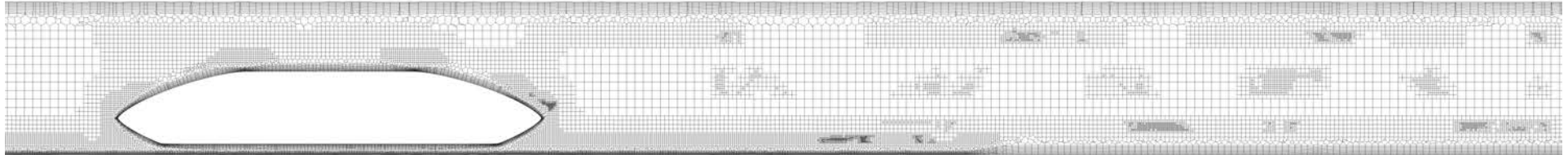
Rear end with  
important changes

Optimized geometry  
Aerodynamic drag reduction about 40%

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## 8. TRANSSONIC REGIME

3.5 Mio de mailles, hex-core adaptative, grad(P) model, kw-SST modified, compressible



Concept\_01, air 100 Pa,  $Av/At = 0.25$

# 8. TRANSSONIC REGIME

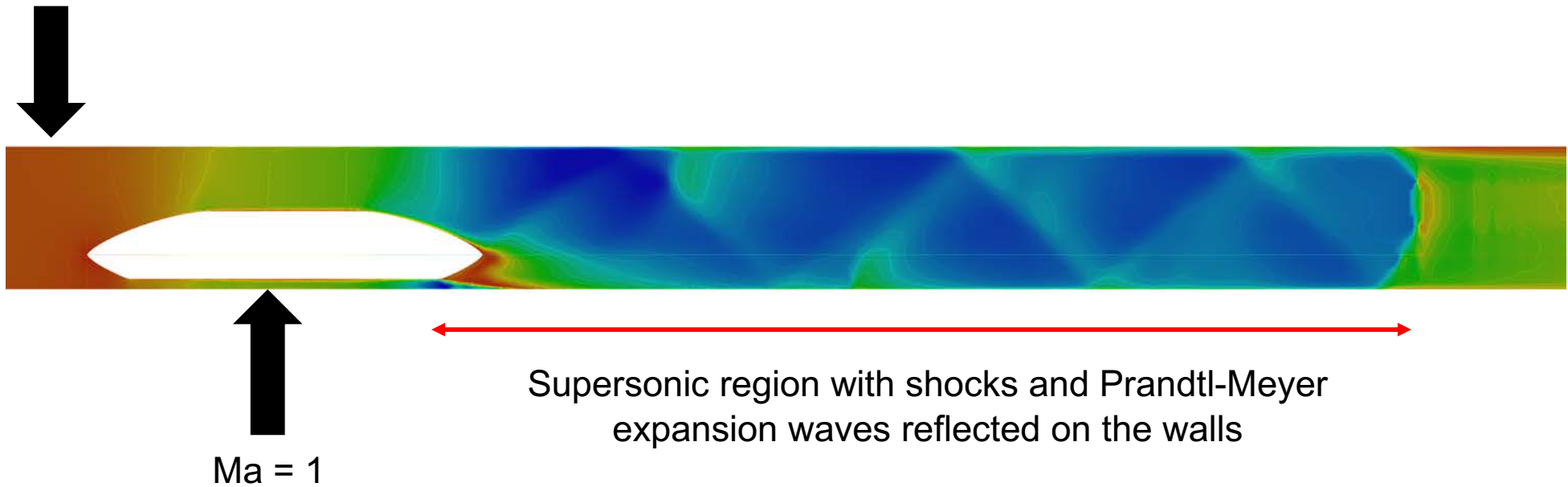
total-temp  
Static Temperature [ K ]



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Increase of P, T

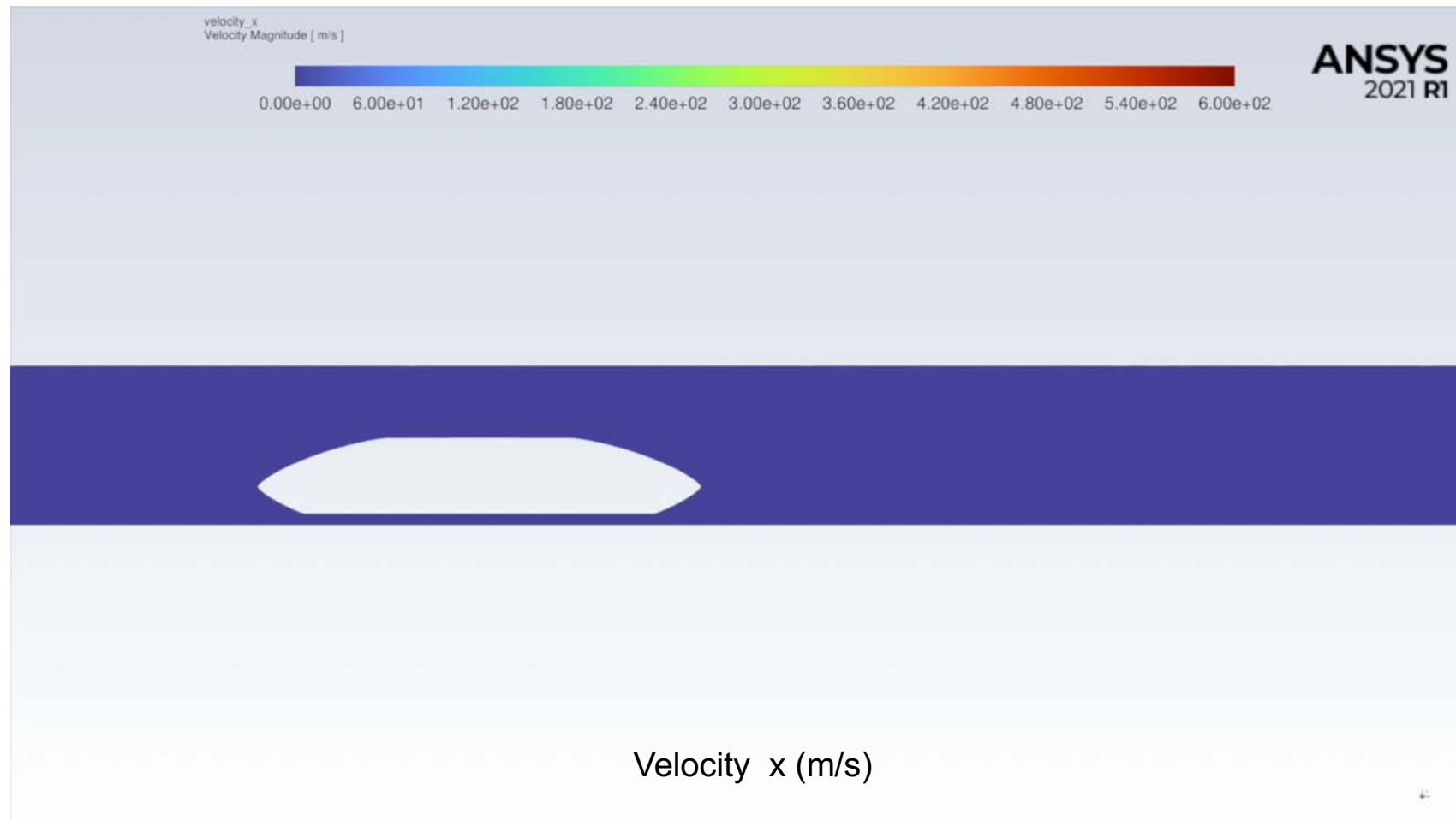
Static temperature (K)



Concept\_01, air 100 Pa, Ma 0.65 (178 m/s or 640 km/h)

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## 8. TRANSSONIC REGIME



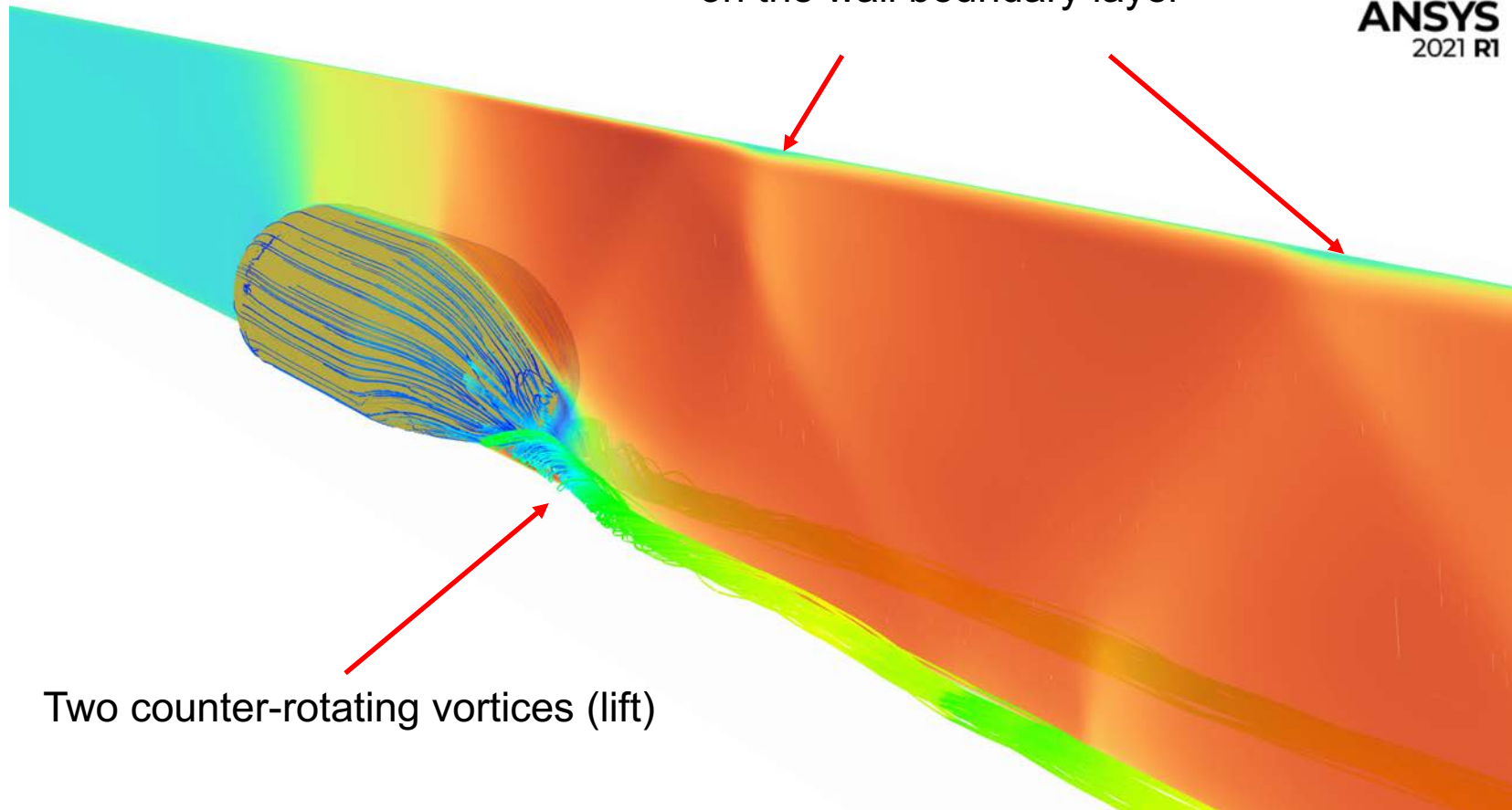
*Concept\_01, air 100 Pa, Ma 0.0-0.8, RB 0.25*

## 8. TRANSSONIC REGIME

Velocity x

Impacts of shocks and expansions  
on the wall boundary layer

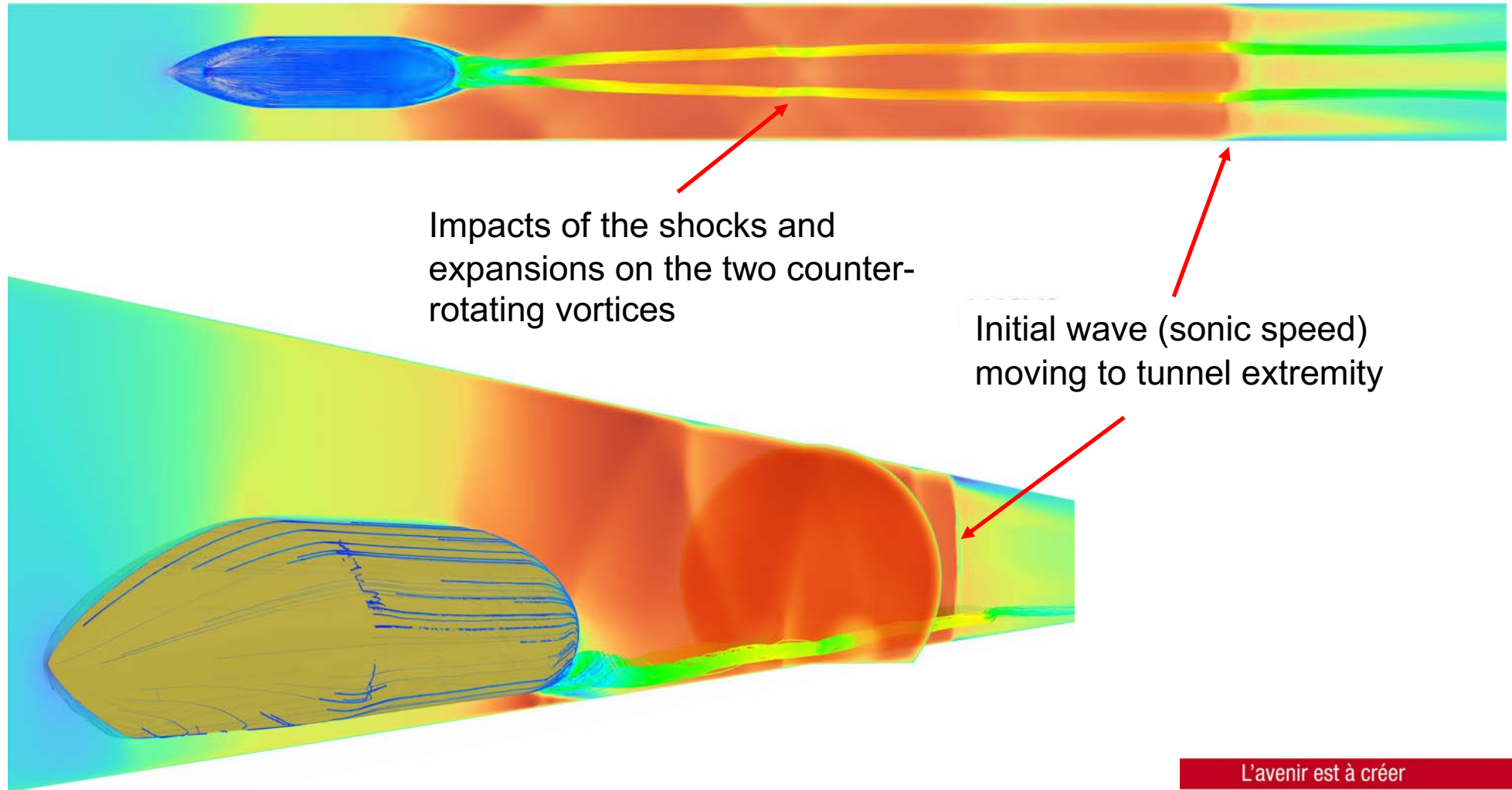
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Two counter-rotating vortices (lift)

Concept\_01, air 100 Pa, Ma 0.65 (178 m/s or 640 km/h)

## 8. TRANSSONIC REGIME



Concept\_01, air 100 Pa, Ma 0.65  
(178 m/s or 640 km/h)

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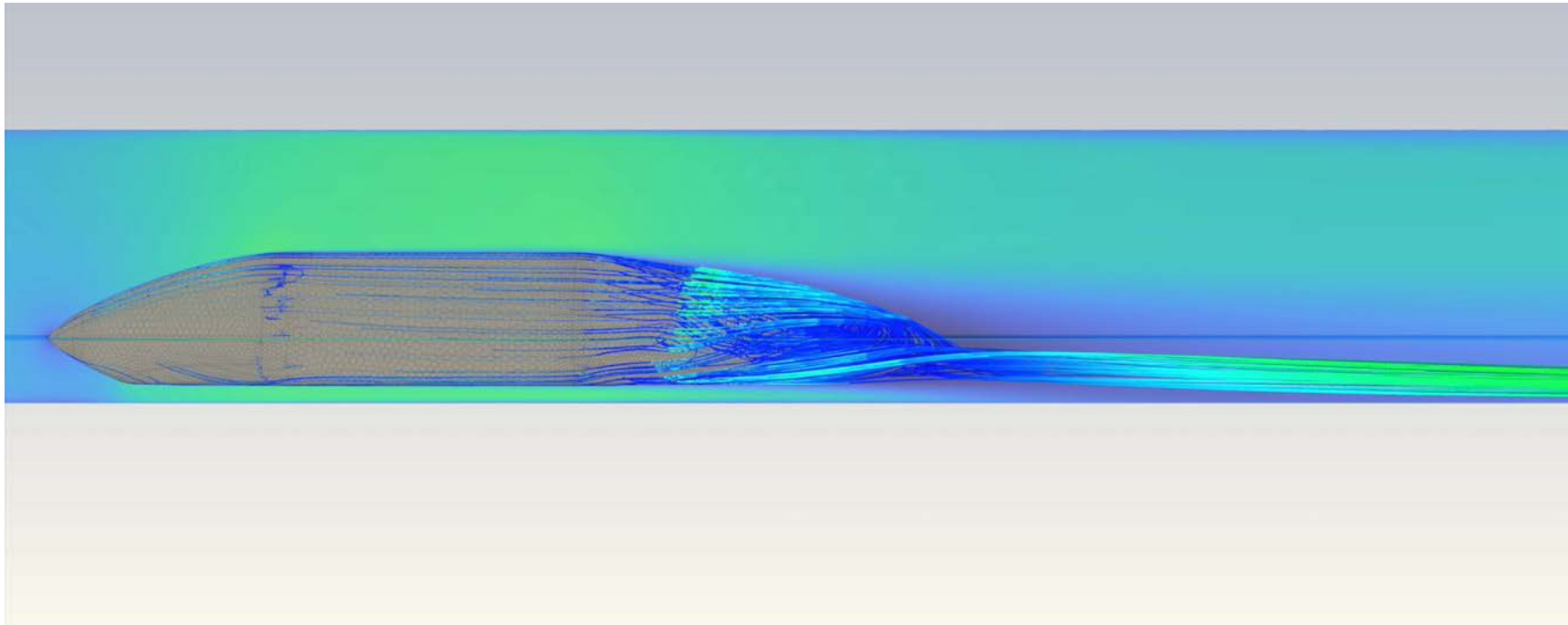
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## 8. TRANSSONIC REGIME

Vehicle moving from Ma 0 to 0.8

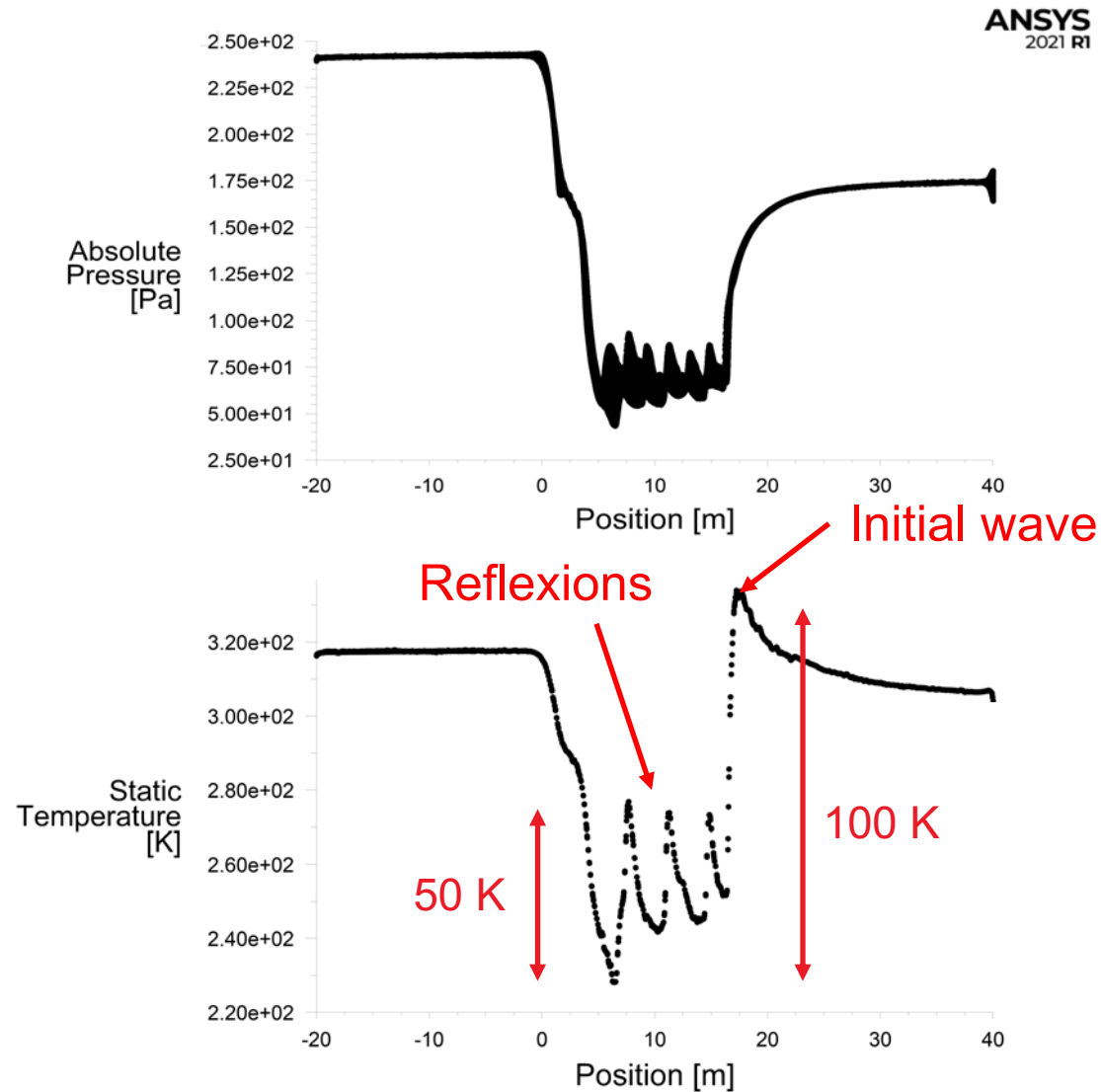


Streamlines colored by velocity (m/s)

*Concept\_01, air 100 Pa, Ma 0.0-0.8, RB 0.25*

## 8. STRESSES ON THE TUNNEL WALLS

In the vicinity of the reflections of the waves on the walls:



Pressures and temperatures on the tunnel walls in transonic regime.



Highlight of the mechanical and thermal stresses

Fatigue loading cases

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## 9. FINAL COMMENTS

### OPTIMAL VEHICLE SPEED DEFINITION

#### Remark :

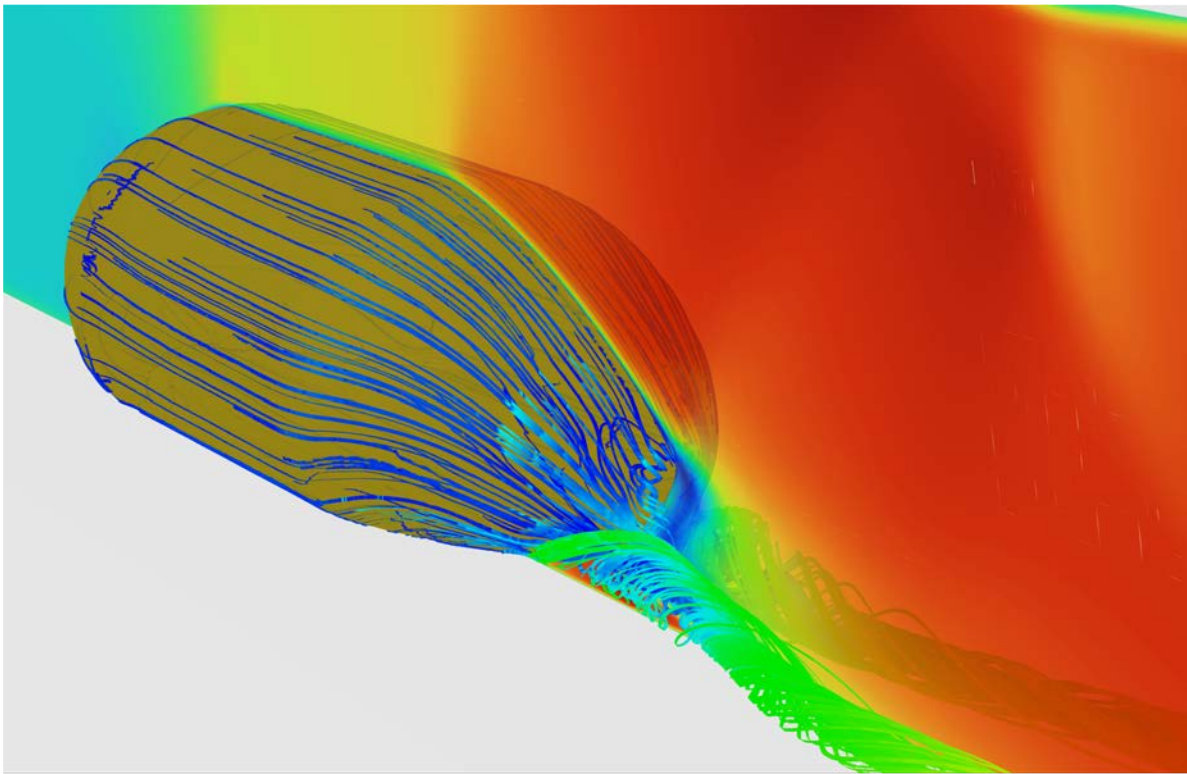
- For magnetically supported systems, there is a strong magnetic drag up to 800 km/h (10 x the aerodynamic drag)
- An optimization « aerodynamics + magnetic resistance » shall be done
  - ➔ The optimal speed is a little beyond the Kantrowitz limit

#### Limitations:

Supersonic effects: Strong temperature and pressure variations in the fluid!

- Can lead to the solidification of the moisture in the gas
- Small ice particles at 1'000 km/h in the tunnel!

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**THANKS! COMMENTS?**

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